

Truss System Disc-type Gripping Unit Series FOUK-TE

TE40

TE40



TE 40 - FR36 - 96 - 0° - HE40

Serial No. Cylinder bore
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Model of finger cylinder

Standard installation 0°
Finger cylinder flip 90°

Flexible compensation unit
No characters Without flexible compensation

Inductive proximity sensor

Used for
gripper
for TG
IPSD-2NS-0823-L3 Inductive, NPN, 3-core3m
IPSD-2PS-0823-L3 Inductive, PNP, 3-core3m

Inductive proximity sensor

Used for
gripper
IPSD-2NS-0823-L3 Inductive, NPN, 3-core3m
IPSD-2PS-0823-L3 Inductive, PNP, 3-core3m
D-M9NAL Magnetic, NPN, 3-core3m
D-M9PAL Magnetic, PNP, 3-core3m

Magnetic proximity sensor

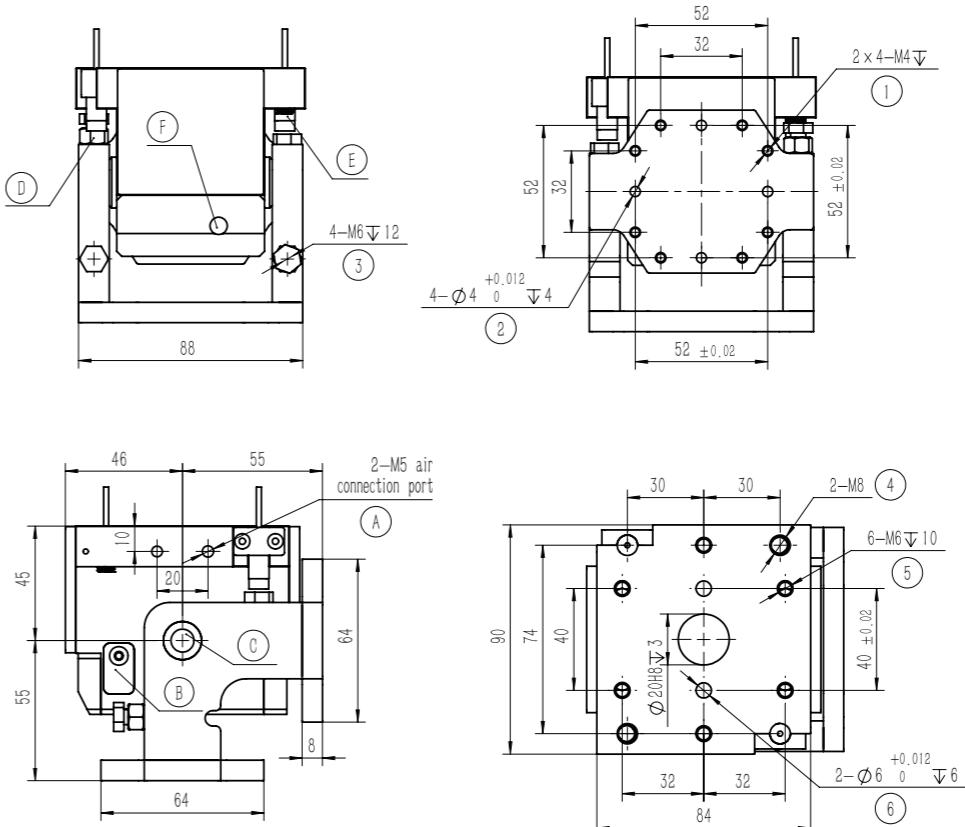
*It is recommended to use two sensors for each rotating unit, and it is recommended to use two sensors for each gripper. For details, see the sensor appendix.

TE40 Rotating unit

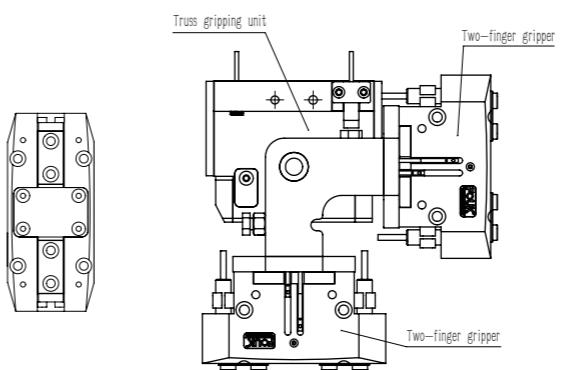
Product attributes	Parameter Value	Unit
Effective torque	2*P	N·m
Workpiece weight	1.5	kg
Product weight	2.1	kg
Rotation time	0.6~1.1	sec
Air connection port of air distribution pipe	M5	
Buffer unit	M12 × 1-10	
Repeated positioning accuracy	± 0.05	°
Operating air pressure	4~6	bar
Operating temperature range	-5~60	°C
IP rating	65	

FR36-96 Gripper

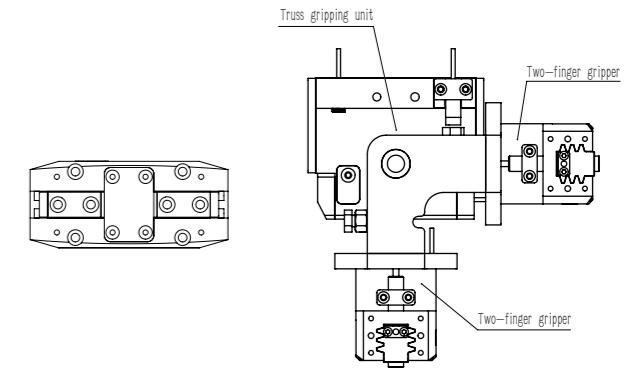
Product attributes	Parameter Value	Unit
Single stroke	8	mm
Product weight	0.5	kg
Maximum allowable gripping distance	110	mm
Specification of air connection port	M5	
Theoretical maximum gripping force: opening/closing	100P/92P	N
Opening/closing time	0.035/0.035	s
Repeated gripping accuracy	± 0.02	mm
Operating air pressure range	3~8	bar
Temperature range of application	-5~60	°C
IP rating	45	



TE40-FR36-96-0° Standard installation



TE40-FR36-96-90° Finger cylinder flip



TE40-HE40

